

φ 40 Body Standard / Hollow Shaft Type

Diameter φ 40mm Shaft type/Hollow type/Built-in type INCREMENTAL Rotary encoder

■ Features

- Easy installation at narrow space
- Small inertia moment
- Wide range of power source :
5VDC, 12-24VDC ±5%
- Various output types

⚠ Please read "Caution for your safety" in operation manual before using.



■ Ordering information

E40 **H** **8** **5000** **3** **2** **24**

Series	Shaft type	Hollow type	Pulse/1 Revolution	Output phase	Output	Power supply	Cable
S: Shaft type	Outside	Inside	See resolution	2:A, B 3:A, B, Z 4:A, \bar{A} , B, \bar{B} 6:A, \bar{A} , B, \bar{B} , Z, \bar{Z}	1: Totem pole output 2: NPN open collector output 3: Voltage output L: Line driver output(*)	5 :5VDC ±5% 24:12-24VDC ±5%	No mark: Normal type (*) 2C: Cable outgoing connector type
H: Hollow type	(*)	6: φ 6mm 8: φ 8mm					
HB: Hollow built-in type	6: φ 6mm 8: φ 8mm	10: φ 10mm 12: φ 12mm					

*Standard : E40S6-**PULSE**-3-2-24
E40H8-**PULSE**-3-2-24
E40HB8-**PULSE**-3-2-24 } 12-24VDC

*Standard:A, B, Z *The power of Line driver is only for 5VDC

*Cable length : 200mm

■ Specifications

Item		Diameter φ40mm shaft type Incremental Rotary encoder		
Resolution(P/R)		(*Note1) *1, *2, *5, 10, *12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 150, 192, 200, 240, 250, 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1500, 1800, 2000, 2048, 2500, 3000, 3600, 5000 (Not indicated type is available to customize)		
Electrical specification	Phase difference of output	Output between A and B phase : $\frac{T}{4} \pm \frac{T}{8}$ (T=1cycle of A phase)		
	Control output	Totem pole output	• Low ⇔ Load current : Max. 30mA, Residual voltage : Max. 0.4VDC • High ⇔ Load current : Max. 10mA, Output voltage : Min. (Power supply-1.5)VDC	
		NPN open collector output	Load current : Max. 30mA, Residual voltage : Max. 0.4VDC	
		Voltage output	Load current : Max. 10mA, Residual voltage : Max. 0.4VDC	
		Line driver output	Low ⇔ Load current : Max. 20mA, Residual : Max. 0.5V High ⇔ Load current : Max. -20mA, Output voltage : Min. 2.5V	
	Response time (Rise/Fall)	Totem pole output	Max. 1μs	• Measuring condition ⇔ Cable length : 2m, I sink = Max. 20mA
		NPN open collector output	Max. 1μs	
		Voltage output	Max. 1μs	
		Line driver output	Max. 0.5μs	
	Max. Response frequency		180kHz	
Current consumption		Max. 60mA(disconnection of the load), Line driver output:Max. 50mA(disconnection of the load)		
Insulation resistance		Min. 100MΩ (at 500VDC)		
Dielectric strength		750VAC 50/60Hz for 1 minute (Between all terminals and case)		
Connection		Cable outgoing type, 200mm cable outgoing connector type		
Mechanical specification	Starting torque	Shaft Type : Max. 40gf · cm(0.004N · m), Holl Type : Max. 50gf · cm(0.005N · m)		
	Moment of inertia	Max. 40g · cm ² (2×40 ⁻⁶ kg · m ²)		
	Shaft loading	Radial : Max. 2kgf, Thrust : Max. 1kgf		
	Deviation of shaft position	Radial : Max. 0.1mm, Thrust : Max. 0.2mm		
	Max. allowable revolution	(*Note2)	5000rpm	
Vibration		1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 2 hours		
Shock		Max. 50G		
Ambient temperature		-10 ~ 70℃ (at non-freezing status), Storage:-25 ~ 85℃		
Ambient humidity		35~85%RH, Storage: 35~90%RH		
Protection		IP50 (IEC specification)		
Cable		5P, φ 5mm, Length : 2m, Shield cable (Line driver output : 8P, φ 5mm)		
Accessory		φ 6mm coupling standard, φ 8mm coupling (Option) [Applied only for shaft type]		
Weight		Approx. 120g		
Approval		CE (Except Line driver output)		

* (*Note1) * pulse is only for A, B phase (Line Driver output is A, \bar{A} , B, \bar{B} phase)

* (*Note2) Max. allowable revolution ≥ Max. response revolution [Max. response revolution (rpm) = $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}$]

Please select the resolution to make lower max. revolution than max. allowable revolution.

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/Speed/Pulse meter

(G) Display unit

(H) Sensor controller

(I) Proximity sensor

(J) Photo electric sensor

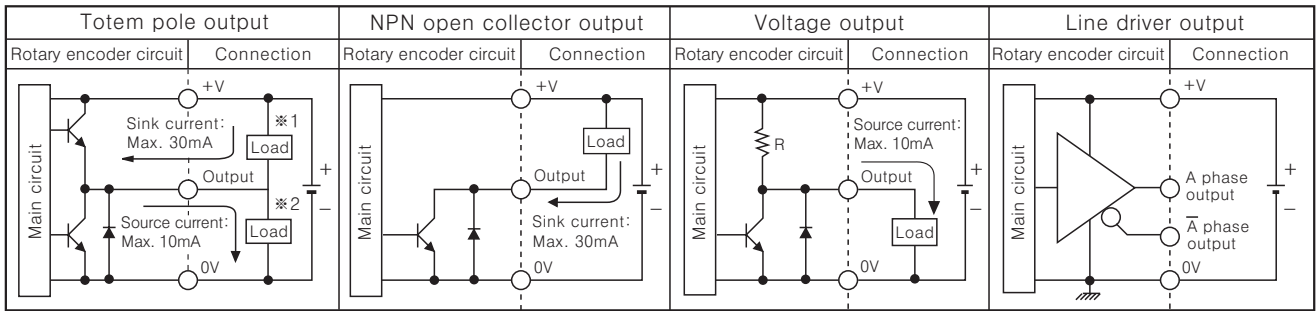
(K) Pressure sensor

(L) Rotary encoder

(M) 5-Phase stepping motor & Driver & Controller

E40 Series

Control output diagram

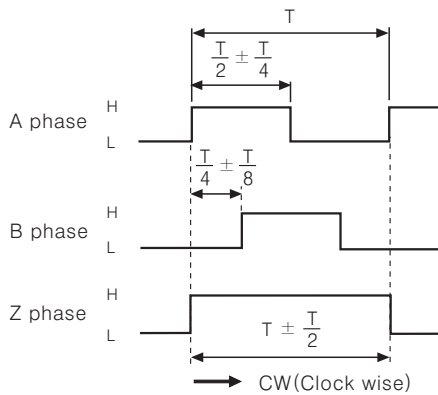


☞ Totem pole output type can be used for NPN open collector output type(*1) or Voltage output type(*2).

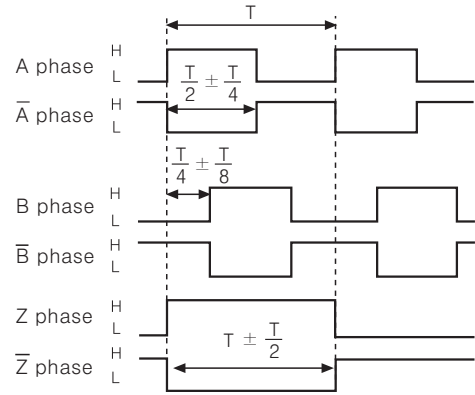
☞ All output circuits are the same A, B, Z phase(Line driver output is A, \bar{A} , B, \bar{B} , Z, \bar{Z})

Output waveform

- Totem pole output / NPN open collector output / Voltage output
- Line driver output



*Inverse type of Z phase is optional.

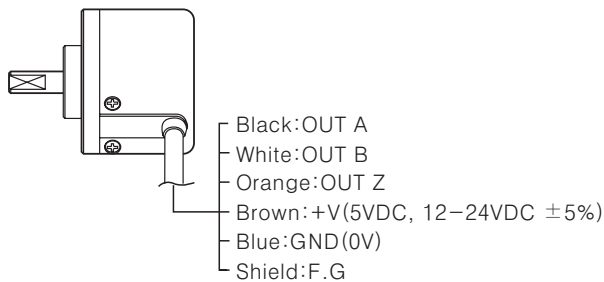


*CW : In a view of shaft

Connections

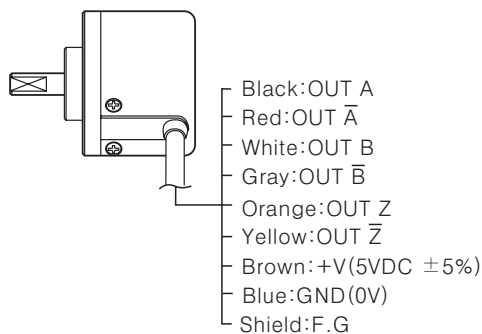
Normal type

- Totem pole output / NPN open collector output / Voltage output

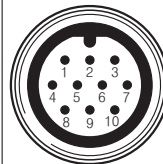


- *Unused wires must be insulated.
- *The body of encoder is connected to a shield.

- Line driver output



Cable outgoing connector type



Pin No.	Cable color	Totem pole output NPN open collector output Voltage output	Line driver output
①	Black	OUT A	OUT A
②	Red	N.C	OUT \bar{A}
③	Brown	+V	+V
④	Blue	GND	GND
⑤	White	OUT B	OUT B
⑥	Gray	N.C	OUT \bar{B}
⑦	Orange	OUT Z	OUT Z
⑧	Yellow	N.C	OUT \bar{Z}
⑨	Shield	F.G	F.G
⑩	Purple	N.C	N.C

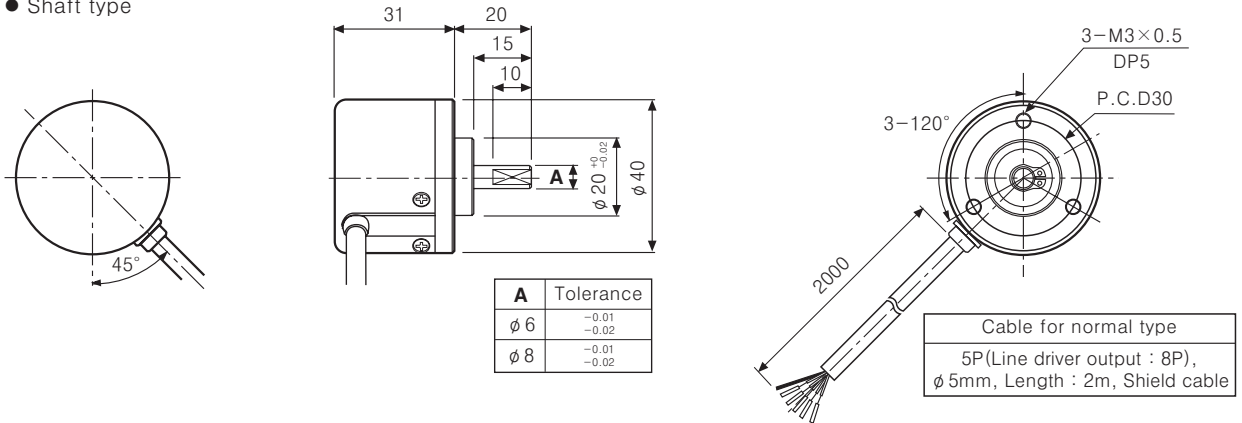
- *N.C(Not Connected)
- *F.G(Field Ground)

φ 40 Body Standard / Hollow Shaft Type

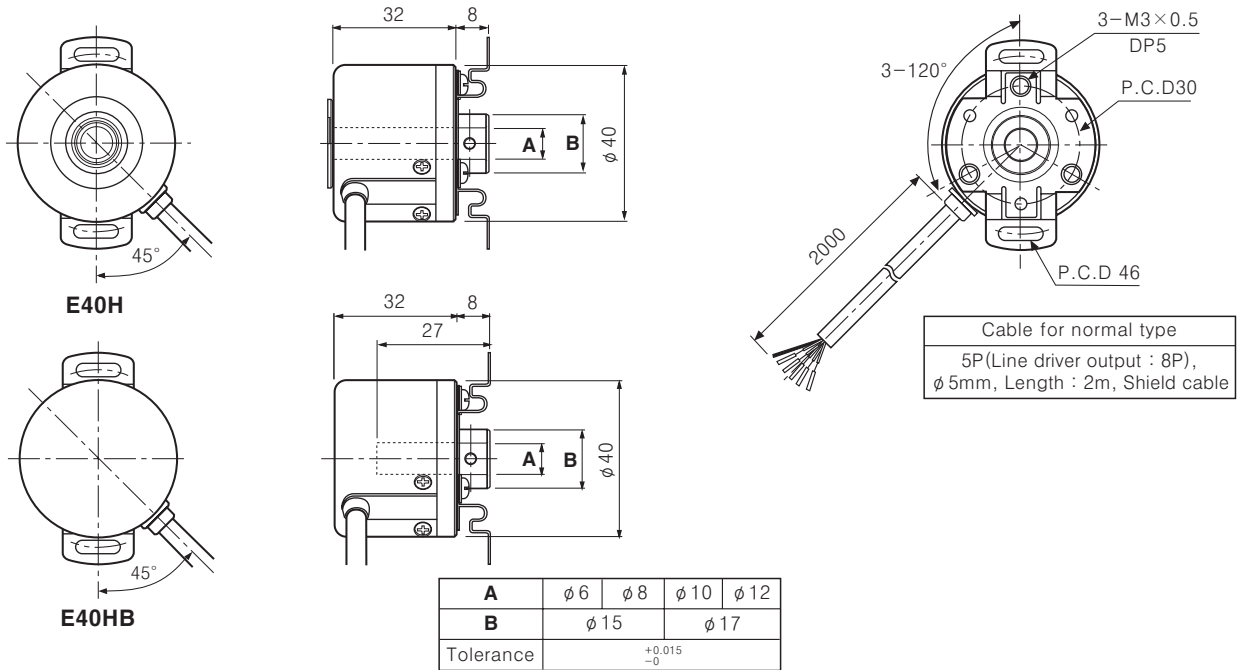
Dimensions

Normal type

Shaft type

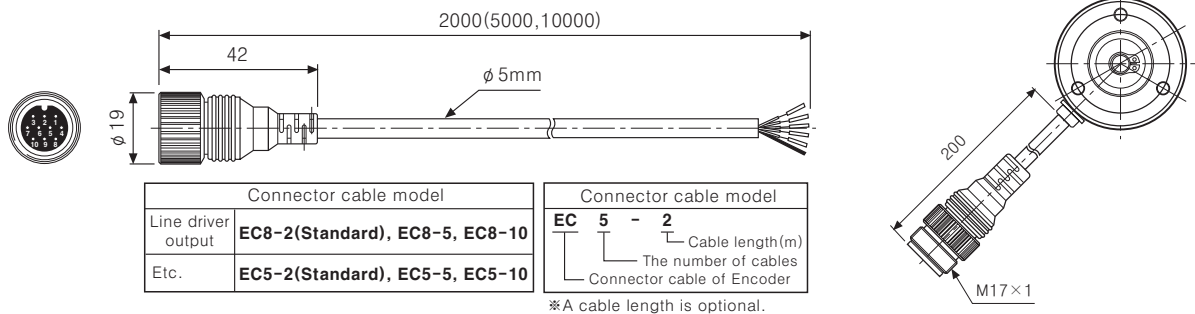


Hollow shaft / Hollow shaft built-in type



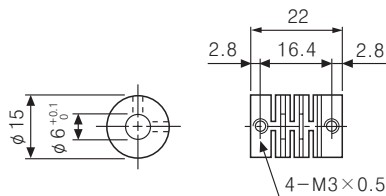
Cable outgoing connector type

Connector cable(Accessory)

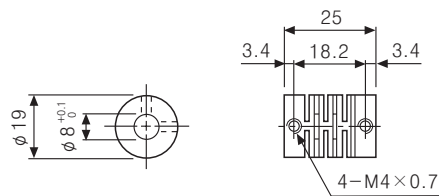


Coupling(E40S)

[φ 6 Coupling]



[φ 8 Coupling]



Unit:mm

(A)
Counter

(B)
Timer

(C)
Temp.
controller

(D)
Power
controller

(E)
Panel
meter

(F)
Tacho/
Speed/
Pulse
meter

(G)
Display
unit

(H)
Sensor
controller

(I)
Proximity
sensor

(J)
Photo
electric
sensor

(K)
Pressure
sensor

(L)
Rotary
encoder

(M)
5-Phase
stepping
motor &
Driver &
Controller